

On conformal vector fields on Einstein Finsler manifolds

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Abstract. In this paper, we study conformal vector fields on Finsler manifolds. Let (M, \mathbf{g}) be an Einstein-Finsler manifold of dimension $n \geq 2$. Suppose that V is conformal vector field on M . We find a condition under which V reduces to a concircular vector field.

Keywords: Finsler metric, Einstein manifold, geodesic circle, concircular transformation, concircular vector field.

1. Introduction

A geodesic circle in an Euclidean space is a straight line or a circle with finite positive radius, which can be generalized naturally to Riemannian or Finsler geometry. Firstly, in 1940, Yano introduced concircular transformations on Riemannian manifolds [28]. Exactly, a geodesic circle in a Riemannian manifold, as well as in a Finsler manifold, is a curve with constant first Frenet curvature and zero second one. In other words, a geodesic circle is a torsion free curve with constant curvature. A concircular transformation on a Riemannian manifold is a conformal transformation which preserves geodesic circles ([12], [28]). Many researchers have developed the theory of concircular transformations to different contents ([13, 14, 25]). In 1970, Vogel showed that every concircular transformation on a Riemannian manifold is conformal [26]. This notion has been extended to Finsler geometry by Agrawal and Izumi [1]. Also, a similar result is proved by Bidabad-Shen in 2012 [5]. That is, every transformation

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which preserves geodesic circles reduces to a conformal transformation. So, by the modified definition, a diffeomorphism φ , between two Finsler manifolds (M, F) and (\tilde{M}, \tilde{F}) , is said to be concircular if it maps geodesic circles to geodesic circles. Also, two Finsler metrics defined on a manifold are said to be concircular if they have the same geodesic circles.

In [4], Bidabad-Joharinad studied conformal vector fields on Finsler spaces. They showed that every vector field on a Finsler space which keeps geodesic circles (concircular vector fields) invariant is conformal. An arbitrary vector field $V = v^i(x)\partial/\partial x^i$ on a Finsler manifold (M, \mathbf{g}) is said to be concircular if

$$\mathcal{L}_{\hat{V}}\mathbf{g} = 2\rho\mathbf{g}, \quad \nabla\rho + \mathbf{g}(G, \hat{\nabla}\rho) = \phi\mathbf{g}, \tag{1.1}$$

where, ∇ and $\hat{\nabla}$ are the Cartan horizontal and vertical covariant derivatives respectively. Also, $\rho = \rho(x)$ is a real function on M called characteristic function of V . Here, \hat{V} is the complete lift of V , i.e., $\hat{V} = v^i(x)\partial/\partial x^i + y^j(\partial_j v^i)\partial/\partial y^i$. They find a necessary and sufficient condition for a vector field to keep geodesic circles invariant. This leads to a significant definition of concircular vector fields on a Finsler space. They classified complete Finsler spaces admitting a special conformal vector fields.

The Liouville theorem explains that every conformal transformation between two open neighborhoods of n -dimensional Euclidean-space ($n \geq 3$) is a combination of inversion and similarity. In [6], Brinkmann proved that a conformal transformation of an Einstein metric on the Riemannian manifold (M, \mathbf{g}) remains Einstein if and only if the gradient of the conformal characteristic function ρ of this transformations satisfies the ODE: $D_i D_j \rho + k\rho g_{ij} = 0$, where D is the Levi-Civita connection and $k = k(x)$ is a constant equal to the scalar curvature. In [28], Yano proved that the ODE holds for the characteristic function of a conformal transformation if and only if this transformation, which he called concircular, leaves invariant geodesic circles.

An n -dimensional Finsler manifold (M, F) is called an Einstein manifold if $\mathbf{Ric} = (n - 1)k(x)F^2$, where $k = k(x)$ is a scalar function on M . In this paper, we study conformal vector fields on Einstein Finsler manifold and prove the following.

Theorem 1.1. *Let (M, F) be an Einstein Finsler manifold. Then every conformal vector field V on M reduces to a concircular vector field (1.1) if and only if there are scalar functions $\lambda = \lambda(x)$ and $\Psi = \Psi(x, y)$ on M and TM , respectively, such that the following hold:*

$$2(n - 2)(\lambda g_{ij} - \dot{A}^r_{ij}\rho_r) + \left[\Psi + 4(n - 1)k\rho \right] g_{ij} + \Psi_{ij}F^2 + 2(\Psi_i y_j + \Psi_j y_i) = 0, \tag{1.2}$$

$$\rho^r C^k_{ri} = 0. \tag{1.3}$$

where $C_{r_i}^k$ and \dot{A}^r_{ij} denote the Cartan torsion and Landsberg curvature of F . Here, $y_i := FF_{y^i}$, $\rho_r := \partial\rho/\partial x^r$, $\rho^r := g^{ri}\rho_i$, $\Psi_i := \Psi_{y^i}$ and $\Psi_{ij} := \Psi_{y^i y^j}$.

2. Preliminary

Let M be an n -dimensional C^∞ manifold. We denote by $\pi : TM \rightarrow M$ the bundle of tangent vectors and by $\pi_0 : TM_0 \rightarrow M$ the fiber bundle of non-zero tangent vectors. A Finsler structure on M is a function $F : TM \rightarrow [0, \infty)$, with the following properties:

- i) F is C^∞ on $TM_0 := TM - \{0\}$;
- ii) $F(x, y)$ is positively homogeneous of degree one in y , i.e. $F(x, \lambda y) = \lambda F(x, y)$, $\forall \lambda > 0$, where we denote an element of TM by (x, y) ;
- iii) The Hessian matrix of $F^2/2$ is positive definite on TM_0 ;

$$g_{ij} := \frac{1}{2} \frac{\partial^2 F^2}{\partial y^i \partial y^j}.$$

A Finsler manifold (M, g) is a pair of a differential manifold M and a tensor field $g = (g_{ij})$ on TM which defined by a Finsler structure F .

Let $x \in M$ and $F_x := F|_{T_x M}$. To measure the non-Euclidean feature of F_x , define $\mathbf{C}_y : T_x M \times T_x M \times T_x M \rightarrow \mathbb{R}$ by

$$\mathbf{C}_y(u, v, w) := \frac{1}{2} \frac{d}{dt} \left[\mathbf{g}_{y+tw}(u, v) \right] \Big|_{t=0}, \quad u, v, w \in T_x M.$$

The family $\mathbf{C} := \{\mathbf{C}_y\}_{y \in TM_0}$ is called the Cartan torsion. By definition, \mathbf{C}_y is a symmetric trilinear form on $T_x M$. It is well known that $\mathbf{C} = 0$ if and only if F is Riemannian.

The spray of a Finsler structure F is a vector field on TM as:

$$\mathbf{G} = y^i \frac{\partial}{\partial x^i} - 2G^i \frac{\partial}{\partial y^i}. \quad (2.1)$$

where G^i are called the spray (or geodesic) coefficients

$$G^i = \frac{1}{4} g^{il} \left\{ F_{x^m y^l}^2 y^m - F_{x^l}^2 \right\} \quad (2.2)$$

and $(g^{ij}) := (g_{ij})^{-1}$. The geodesics of F are characterized by the second order differential equation:

$$\frac{d^2 c^i}{dt^2} + 2G^i(c(t), \dot{c}(t)) = 0.$$

For $y \in T_x M_0$, define $\mathbf{B}_y : T_x M \times T_x M \times T_x M \rightarrow T_x M$ by $\mathbf{B}_y(u, v, w) := B^i_{jkl}(y) u^j v^k w^l \frac{\partial}{\partial x^i} \Big|_x$ where

$$B^i_{jkl} := \frac{\partial^3 G^i}{\partial y^j \partial y^k \partial y^l}.$$

The quantity \mathbf{B} is called the Berwald curvature of the Finsler metric F . We call a Finsler metric F a Berwald metric, if $\mathbf{B} = 0$.

For $y \in T_x M$, define the Landsberg curvature $\dot{\mathbf{A}}_y : T_x M \times T_x M \times T_x M \rightarrow \mathbb{R}$ by

$$\dot{\mathbf{A}}_y(u, v, w) := -\frac{1}{2} \mathbf{g}_y(\mathbf{B}_y(u, v, w), y).$$

F is called a Landsberg metric if $\dot{\mathbf{A}}_y = 0$. By definition, every Berwald metric is a Landsberg metric.

We denote here by G_j^i the coefficients of nonlinear connection on TM , where

$$G_j^i := \frac{\partial G^i}{\partial y^j}.$$

By means of this nonlinear connection tangent space can be split into the horizontal and vertical subspaces with the corresponding basis $\{\frac{\delta}{\delta x^i}, \frac{\partial}{\partial y^i}\}$, which are related to the typical bases of TM , $\{\frac{\partial}{\partial x^i}, \frac{\partial}{\partial y^i}\}$, by

$$\frac{\delta}{\delta x^i} := \frac{\partial}{\partial x^i} - G_i^j \frac{\partial}{\partial y^j},$$

where

$$\Gamma_{jk}^i = \frac{1}{2} g^{il} \left(\frac{\delta g_{jl}}{\delta x^k} + \frac{\delta g_{kl}}{\delta x^j} - \frac{\delta g_{jk}}{\delta x^i} \right).$$

The components of the hh -curvature of Chern connection are expressed here by

$$R_{jkl}^i = \frac{\delta \Gamma_{jl}^i}{\delta x^k} + \frac{\delta \Gamma_{jk}^i}{\delta x^l} - \Gamma_{hk}^i \Gamma_{jl}^h - \Gamma_{hl}^i \Gamma_{jk}^h.$$

Here, we denote by ∇ and $\dot{\nabla}$, horizontal and vertical covariant derivatives in Cartan connection.

The following relations between Chern connection ∇ and Berwald connections D hold

$$\begin{aligned} D_i Y^k &= \nabla_i Y^k + \nabla_0 C_{ir}^k Y^r = \nabla_i Y^k + L_{ir}^k Y^r \\ D_i Y_k &= \nabla_i Y_k + \nabla_0 C_{kir} Y^r = \nabla_i Y^k - L_{kir} Y^r \\ &= \nabla_i Y^k - L_{ki}^r Y_r \end{aligned} \quad (2.3)$$

The Riemann curvature $R_y : T_p M \rightarrow T_p M$ is a linear transformations on tangent spaces, which is defined by

$$R_y = R_k^i dx^k \otimes \frac{\partial}{\partial x^i} \quad (2.4)$$

$$R_k^i := 2 \frac{\partial G^i}{\partial x^i} - y^j \frac{\partial^2 G^i}{\partial x^j \partial y^k} + 2G^j \frac{\partial^2 G^i}{\partial y^j \partial y^k} - \frac{\partial G^i}{\partial y^j} \frac{\partial G^j}{\partial y^k}. \quad (2.5)$$

For a two-dimensional plane $P \subset T_pM$ and $y \in T_pM \setminus \{0\}$ such that $P = \text{span}\{y, u\}$, the pair $\{P, y\}$ is called a flag in T_pM . The flag curvature $\mathbf{K}(P, y)$ is defined by

$$\mathbf{K}(P, y) := \frac{\mathbf{g}_y(u, R_y(u))}{\mathbf{g}_y(y, y)\mathbf{g}_y(u, u) - \mathbf{g}_y(y, u)^2}.$$

We say that F is of scalar curvature if for any $y \in T_pM \setminus \{0\}$ the flag curvature $\mathbf{K}(P, y) = \lambda(y)$ is independent of P containing y . This is equivalent to the following condition in a local coordinate system (x^i, y^i) in TM :

$$R_k^i = \lambda F^2 \{\delta_k^i - F^{-1} F_{y^k} y^i\}.$$

If λ is a constant, then F is said to be of constant curvature.

Let (M, \mathbf{g}) be a Finsler manifold. A vector field $V = v^i(x) \frac{\partial}{\partial x^i}$ on M is said to be concircular if

$$\begin{aligned} \mathcal{L}_{\hat{V}} \mathbf{g} &= 2\rho \mathbf{g}, \\ \nabla \rho + \mathbf{g}(G, \dot{\nabla} \rho) &= \phi \mathbf{g}, \end{aligned} \quad (2.6)$$

where ∇ and $\dot{\nabla}$ are the Cartan horizontal and vertical covariant derivatives, respectively, and ϕ is a smooth function on M . Here,

$$\hat{V} = v^i(x) \frac{\partial}{\partial x^i} + y^j (\partial_j v^i) \frac{\partial}{\partial y^i}$$

is the complete lift of V . For the other vector fields see [18].

In a local coordinate system equation (2.6) is written in the following form

$$\nabla_k \rho_l + G_k^j \dot{\nabla}_j \rho_l = \phi g_{kl}. \quad (2.7)$$

The vector field V is said to be concircular, if its local flow preserves geodesic circles. V is said to be a conformal vector field or an infinitesimal conformal transformation, if it satisfies

$$\mathcal{L}_{\hat{V}} g_{ij} = 2\rho(x) g_{ij},$$

where $\rho(x)$ is a real function on M called characteristic function of V . If $\rho(x)$ is constant or zero, then V is said to be homothetic or Killing.

In [4], Bidabad-Joharinad studied conformal vector fields on Finsler spaces. They showed that every vector field on a Finsler space which keeps geodesic circles invariant is conformal. They find a necessary and sufficient condition for a vector field to keep geodesic circles invariant. This leads to a significant definition of concircular vector fields on a Finsler space. They classified complete Finsler spaces admitting a special conformal vector fields.

In [23], Shen-Yang found a necessary and sufficient condition for a conformal vector field to be concircular vector field. On a Finsler manifold, a conformal vector field with the conformal factor ρ is concircular if and only if ρ satisfies

$$\rho_{i|j} = \lambda g_{ij}, \quad \rho^r C_{ri}^k = 0, \quad (2.8)$$

where

$$\rho_i := \rho_{x^i}, \quad \rho^i := g^{ir} \rho_r,$$

and $\lambda = \lambda(x)$ is a scalar function on M and the symbol “|” means the horizontal covariant derivative of Cartan (or Chern) connection.

Proposition 2.1. ([4]) *Let V be a conformal vector field on the Finsler manifold (M, \mathbf{g}) . Then the following holds*

$$\begin{aligned} \mathcal{L}_{\hat{V}}(\mathbf{Ric})_{ij} = & -(n-2) \left(\nabla_i \nabla_j \rho - \rho_m \dot{A}_{ij}^m \right) - \Psi g_{ij} - y_i \Psi_j \\ & - y_j \Psi_i - \frac{1}{2} F^2 \left(\dot{\partial}_i \dot{\partial}_j \Psi \right), \end{aligned} \quad (2.9)$$

where $\Psi = \Psi(x, y)$ is a homogeneous and scalar function on TM of degree zero in y .

Now, we can prove the main result of this paper.

Proof of Theorem 1.1: If V is conformal vector field it satisfies

$$\mathcal{L}_{\hat{V}} g_{ij} = 2\rho(x) g_{ij},$$

where $\rho = \rho(x)$ is a real function on M called characteristic function of V . On the other hand according to the Proposition 2.1 we have (2.9). Contracting (2.9) with $y^i y^j$ implies that

$$\mathcal{L}_{\hat{V}}(\mathbf{Ric}) = -(n-2) \left(\nabla_0 \nabla_0 \rho(x) \right) - \Psi F^2. \quad (2.10)$$

(M, F) is Einstein-Finsler manifold, that is

$$\mathbf{Ric} = (n-1)k(x)F^2$$

for scalar function $k = k(x)$. Thus

$$\mathbf{Ric}_{ij} = (n-1)k(x)g_{ij}. \quad (2.11)$$

Taking a Lie derivative of (2.11) along \hat{V} yields

$$\begin{aligned} \mathcal{L}_{\hat{V}}(\mathbf{Ric}_{ij}) &= (n-1) \left\{ (\mathcal{L}_{\hat{V}} k(x)) g_{ij} + k(x) \mathcal{L}_{\hat{V}} g_{ij} \right\} \\ &= (n-1) \left\{ V.k(x) g_{ij} + 2k(x) \rho(x) g_{ij} \right\}. \end{aligned} \quad (2.12)$$

By (2.10) and (2.12), we get

$$-(n-2) (\nabla_0 \nabla_0 \rho) - \Psi F^2 = (n-1) \left\{ V.k(x) + 2k(x) \rho(x) \right\} F^2. \quad (2.13)$$

(2.13) is equal to following

$$2(n-1)k(x)\rho(x)F^2 + (n-1)V.k(x)F^2 + \Psi F^2 + (n-2)(\nabla_0 \nabla_0 \rho) = 0. \quad (2.14)$$

Taking twice vertical derivative of (2.14) implies that

$$\begin{aligned} 2(n-2)D_i D_j \rho + \Psi g_{ij} + 4(n-1)k(x)\rho(x)g_{ij} + \Psi_{ij} F^2 \\ + 2\Psi_i y_j + 2\Psi_j y_i = 0. \end{aligned} \quad (2.15)$$

According to (2.3), the following holds

$$D_i D_j \rho = \nabla_i \rho_j - L_{ij}^r \rho_r. \quad (2.16)$$

By putting (2.16) in (2.15) we obtain

$$\begin{aligned} 2(n-2)(\nabla_i \rho_j - L_{ij}^r \rho_r) + \Psi g_{ij} + 4(n-1)k(x)\rho(x)g_{ij} \\ + \Psi_{ij} F^2 + 2\Psi_i y_j + 2\Psi_j y_i = 0. \end{aligned} \quad (2.17)$$

By considering (2.8), we get the proof. \square

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