

Generalized η -Ricci solitons on f -Kenmotsu manifolds admitting a quarter symmetric metric connection

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Abstract. In this paper, we study η -Ricci solitons on three-dimensional f -Kenmotsu manifolds with respect to a quarter symmetric metric connection. We obtain some results when the potential vector field is pointwise collinear with the Reeb vector field, conformal Killing vector field and a torqued vector field.

Keywords: Generalized η -Ricci soliton, f -Kenmotsu manifold, quarter symmetric metric connection.

1. Introduction

The concept of semi-symmetric metric connections on a differentiable manifold was introduced by Friedman and Schouten in 1924 [6]. As generalizations of these connections, the quarter symmetric metric connections were introduced by Golab in 1975 [7]. An affine connection $\tilde{\nabla}$ in a Riemannian manifold M is called a quarter symmetric metric connection if the torsion tensor T

$$T(U, V) = \tilde{\nabla}_U V - \tilde{\nabla}_V U - [U, V]$$

fulfills

$$T(U, V) = \eta(V)\phi U - \eta(U)\phi V,$$

where U, V are vector fields, η is a 1-form and ϕ is a $(1, 1)$ -tensor field on M . When $\phi U = U$ the quarter symmetric connection becomes a semi-symmetric connection. If the connection $\tilde{\nabla}$ fulfills

$$(\tilde{\nabla}_U g)(V, W) = 0,$$

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for all vector fields U, V, W on M , then the connection $\tilde{\nabla}$ is called quarter symmetric metric connection; contrarily, it is a non-metric connection.

Quarter symmetric metric connections have been studied extensively by many researchers, see [10],[11],[12],[19].

The notion of f -Kenmotsu manifolds was introduced by Jannsens and Vanhecke in 1981 [9] by considering the f is a real constant. Afterwards, in 1991, Olszak and Rosca defined the f -Kenmotsu manifolds by assuming the f as a function [14]. Here, they studied geometry of normal locally conformal almost cosymplectic manifolds.

On the other hand, let (M, g) be a Riemannian manifold of dimension n , ($n \geq 2$) such that $\{g(t)\}$ is the 1-parameter family of metrics and $S(t)$ is its Ricci tensor. In this case, the equation of Ricci flow is defined by [8]

$$\frac{\partial g(t)}{\partial t} = -2S(t)g(t).$$

The special solutions of the Ricci flow are famous as Ricci solitons. A Ricci soliton is a triplet (g, X, ζ) on a Riemannian manifold satisfying

$$L_X g + 2S + 2\zeta g = 0,$$

where L_X is the Lie derivative in the direction of the potential vector field X , S is the Ricci tensor and ζ is a real constant [1]. The generalized Ricci soliton is defined by

$$L_X g + 2\nu X^b \otimes X^b - 2\alpha S - 2\zeta g = 0,$$

where X^b is the canonical 1-form associated to X [13]. The concept of η -Ricci soliton was defined by Cho and Kimura [5] as

$$L_X g + 2S + 2\zeta g + 2\sigma\eta \otimes \eta = 0.$$

The η -Ricci solitons are generalizations of Ricci solitons. Subsequently, M. D. Siddiqi defined the generalized η -Ricci soliton as [18]

$$L_X g + 2\nu X^b \otimes X^b + 2S + 2\zeta g + 2\sigma\eta \otimes \eta = 0.$$

In the present paper, we give some characterizations about generalized η -Ricci solitons on f -Kenmotsu manifolds admitting quarter symmetric metric connections. Throughout the paper, all geometric objects (curves, manifolds, vector fields, functions etc.) are assumed to be smooth.

2. Preliminaries

2.1. f -Kenmotsu Manifolds. Consider a 3-dimensional manifold M . If the (1,1)-tensor field φ , the vector field ξ , the 1-form η and the Riemannian metric g satisfy the following relations, we say that the quartet (φ, ξ, η, g) is a contact metric structure on M and the quintet $(M, \varphi, \xi, \eta, g)$ is a contact metric

manifold:

$$\begin{aligned}
\eta \circ \varphi &= 0, \\
\varphi \xi &= 0, \\
\eta(\xi) &= 1, \\
g(U, \xi) &= \eta(U), \\
g(U, \varphi V) &= -g(\varphi U, V), \\
g(\varphi U, \varphi V) &= g(U, V) - \eta(U)\eta(V), \\
\varphi^2 U &= -U + \eta(U)\xi,
\end{aligned} \tag{2.1}$$

where U, V are vector fields on M . The contact metric manifold M is called f -Kenmotsu if it fulfills the following relation

$$(\nabla_U \varphi)(V) = f[g(\varphi U, V)\xi - \eta(V)\varphi(U)], \tag{2.2}$$

where f is a function. This gives us

$$\nabla_U \xi = f[U - \eta(U)\xi], \tag{2.3}$$

and

$$(\nabla_U \eta)(V) = f[g(U, V) - \eta(U)\eta(V)]. \tag{2.4}$$

Using (2.3) and (2.4), we obtain

$$\begin{aligned}
R(U, V)\xi &= -(f^2 + \xi(f))[\eta(V)U - \eta(U)V], \\
R(U, \xi)V &= (f^2 + \xi(f))[g(U, V)\xi - \eta(V)U], \\
R(\xi, U)\xi &= -(f^2 + \xi(f))[\eta(U)\xi - U],
\end{aligned}$$

for every vector fields U, V on M . Here, R denotes the Riemannian curvature tensor of M . The Ricci tensor of the f -Kenmotsu manifold M is expressed as

$$S(U, V) = \left(\xi(f) + \frac{r}{2} + f^2\right)g(U, V) - (3\xi(f) + \frac{r}{2} + 3f^2)\eta(U)\eta(V), \tag{2.5}$$

for every vector fields U, V on M . Here, r denotes the scalar curvature of M . From (2.5), we get

$$S(U, \xi) = -2\left(f^2 + \xi(f)\right)\eta(U), \tag{2.6}$$

for every vector fields U on M .

2.2. A quarter symmetric metric connection on a f -Kenmotsu manifold. Let $\tilde{\nabla}$ be an affine connection and ∇ be the Levi-Civita connection of f -Kenmotsu manifold M . The connection $\tilde{\nabla}$ is said to be a quarter symmetric metric connection on M if

$$\tilde{\nabla}_U V = \nabla_U V - \eta(U)\varphi V, \tag{2.7}$$

for every vector fields U, V on M . From (2.1), (2.2) and (2.7), we get

$$(\tilde{\nabla}_U \varphi)V = f[g(\varphi U, V)\xi - \eta(V)\varphi U]. \tag{2.8}$$

From (2.3) and (2.7), we have

$$\tilde{\nabla}_U \xi = f[U - \eta(U)\xi]. \quad (2.9)$$

From (2.4) and (2.7), we occur

$$(\tilde{\nabla}_U \eta)V = fg(\varphi U, \varphi V). \quad (2.10)$$

The curvature tensor \tilde{R} , the Ricci tensor \tilde{S} , the scalar curvature \tilde{r} and the Ricci operator \tilde{Q} of the connection $\tilde{\nabla}$ in (2.7) are given by respectively:

$$\begin{aligned} \tilde{R}(U, V)W &= R(U, V)W + f(\eta(V)\varphi(U) - \eta(U)\varphi(V))\eta(W) \\ &\quad + f(\eta(U)g(\phi V, W) - \eta(V)g(\phi U, W))\xi, \\ \tilde{S}(U, V) &= S(U, V) + fg(\varphi U, V) \\ &= (\xi(f) + \frac{r}{2} + f^2)g(U, V) \\ &\quad - (3\xi(f) + \frac{r}{2} + 3f^2)\eta(U)\eta(V) \\ &\quad + fg(\varphi U, V), \\ \tilde{Q}U &= (\xi(f) + \frac{r}{2} + f^2)U - (3\xi(f) + \frac{r}{2} + 3f^2)\eta(U)\xi + fg\varphi U, \\ \tilde{r} &= r \end{aligned} \quad (2.11)$$

see [2],[15]. We also have

$$\begin{aligned} \tilde{R}(U, V)\xi &= -(f^2 + \xi(f))(\eta(V)U - \eta(U)V) + f(\eta(V)\varphi U - \eta(U)\varphi V), \\ \tilde{R}(\xi, V)\xi &= -(f^2 + \xi(f))(\eta(V)\xi - V) - f\varphi V, \\ \tilde{S}(V, \xi) &= -2(f^2 + \xi(f))\eta(V). \end{aligned}$$

For more details, see [17].

3. Main Results

The generalized η -Ricci soliton with respect to the quarter symmetric metric connection is defined by

$$\alpha\tilde{S} + \frac{\beta}{2}\tilde{L}_X g + \nu X^b \otimes X^b + \sigma\eta \otimes \eta + \zeta g = 0, \quad (3.1)$$

where \tilde{S} is the Ricci tensor of the connection $\tilde{\nabla}$, X^b is the canonical 1-form associated to X , i.e., $X^b(U) = g(U, X)$ for every vector fields U , ζ is a function and $\alpha, \beta, \nu, \sigma$ are real constants satisfying $(\alpha, \beta, \nu) \neq (0, 0, 0)$. The particular cases of the generalized η -Ricci soliton are listed below:

- (a) If $\alpha = 1$, $\nu = \sigma = 0$, we obtain the Ricci soliton.
- (b) If $\alpha = 1$, $\nu = 0$, we obtain the η -Ricci soliton.
- (c) If $\sigma = 0$, we obtain the generalized Ricci soliton.

On the other hand, an f -Kenmotsu manifold is called η -Einstein if

$$S = f_1 g + f_2 \eta \otimes \eta,$$

where f_1, f_2 are functions on M . Now, assume that M is an f -Kenmotsu manifold satisfying the generalized η -Ricci soliton with respect to the quarter symmetric metric connection (3.1). Consider the potential vector field $X = \theta\xi$, in other words, let X be a pointwise collinear with the Reeb vector field ξ . Using (2.9), we get

$$(\tilde{L}_{\theta\xi}g)(U, V) = (U\theta)\eta(V) + (V\theta)\eta(U) + 2f\theta\{g(U, V) - \eta(U)\eta(V)\}, \quad (3.2)$$

for every vector fields U, V on M . It is clear that

$$\xi^b \otimes \xi^b(U, V) = \eta(U)\eta(V). \quad (3.3)$$

Putting $X = \theta\xi$ and the relations (2.11), (3.2), (3.3) in (3.1), we deduce

$$\begin{aligned} & \alpha\left[S(U, V) + fg(U, \varphi V)\right] + \frac{\beta}{2}\left\{(U\theta)\eta(V) + (V\theta)\eta(U)\right\} \\ & + \beta f\theta\left\{g(U, V) - \eta(U)\eta(V)\right\} + (\nu\theta^2 + \sigma)\eta(U)\eta(V) + \zeta g(U, V) = 0. \end{aligned} \quad (3.4)$$

Taking $V = \xi$ in (3.4) and using (2.6) we obtain

$$\alpha\left[-2(f^2 + \xi(f))\eta(U)\right] + \frac{\beta}{2}U(\theta) + \frac{\beta}{2}\xi(\theta)\eta(U) + (\nu\theta^2 + \sigma + \zeta)\eta(U) = 0. \quad (3.5)$$

Taking $U = \xi$ in (3.5) we get

$$\beta\xi(\theta) = 2\alpha(f^2 + \xi(f)) - (\nu\theta^2 + \sigma + \zeta). \quad (3.6)$$

Substituting (3.6) in (3.5) we have

$$\beta U(\theta) = [2\alpha(f^2 + \xi(f)) - (\nu\theta^2 + \sigma + \zeta)]\eta(U),$$

which leads to

$$\beta d\theta = \left[2\alpha(f^2 + \xi(f)) - (\nu\theta^2 + \sigma + \zeta)\right]\eta. \quad (3.7)$$

Putting (3.7) in (3.4) we get

$$\alpha\tilde{S}(U, V) = \left(\zeta + \beta f\theta\right)\left[-g(U, V) + \eta(U)\eta(V)\right]. \quad (3.8)$$

Equation (3.8) gives us

$$\alpha\tilde{r} = -2\zeta - 2\beta f\theta.$$

Now, we can express the following theorem and corollary.

Theorem 3.1. *Let $(M, g, \varphi, \xi, \eta)$ be an f -Kenmotsu manifold admitting the quarter symmetric metric connection defined by (2.7). If M is a generalized η -Ricci soliton with the septet $(g, X, \alpha, \beta, \nu, \sigma, \zeta)$ such that $\alpha \neq 0$ and $X = \theta\xi$ for a function θ on M , then M is an η -Einstein soliton and an η -Einstein manifold with respect to the quarter symmetric metric connection.*

Corollary 3.2. *Let $(M, g, \varphi, \xi, \eta)$ be an f -Kenmotsu manifold admitting the quarter symmetric metric connection defined by (2.7). If M is a generalized η -Ricci soliton with the septet $(g, X, \alpha, \beta, \nu, \sigma, \zeta)$ such that $\alpha \neq 0$ and $X = \theta\xi$ for a function θ on M , then $\alpha\tilde{r} = -2\zeta - 2\beta f\theta$.*

Now, we recall the definition of the conformal Killing and torse-forming vector fields and give some results about them.

Definition 3.3. A vector field X is called a conformal Killing vector field if

$$(L_X g)(U, V) = 2hg(U, V),$$

for every vector fields U, V , where h is a function. The particular cases of a conformal Killing vector field are listed below:

- (i) If $h = 0$, we obtain Killing vector fields.
- (ii) If h is a constant, we obtain homothetic vector fields.
- (iii) If h is not a constant, we obtain proper vector fields.

Suppose that X is called a conformal Killing vector field with respect to the quarter symmetric metric connection $\tilde{\nabla}$, i.e.,

$$(\tilde{L}_X g)(U, V) = 2hg(U, V).$$

By (3.1), we have

$$\alpha\tilde{S}(U, V) + \beta hg(U, V) + \nu X^b(U)X^b(V) + \sigma\eta(U)\eta(V) + \zeta g(U, V) = 0. \quad (3.9)$$

Taking $V = \xi$ in (3.9), we get

$$g\left(-2(f^2 + \xi(f))\xi + \beta h\xi + \nu\eta(X)X + \sigma\xi + \zeta\xi, U\right) = 0.$$

So, we have

Theorem 3.4. Let $(M, g, \varphi, \xi, \eta)$ be an f -Kenmotsu manifold admitting the quarter symmetric metric connection defined by (2.7). If M is a generalized η -Ricci soliton with the septet $(g, X, \alpha, \beta, \nu, \sigma, \zeta)$ such that X is a conformal Killing vector field, then

$$\left[-2(f^2 + \xi(f)) + \beta h + \sigma + \zeta\right]\xi + \nu\eta(X)X = 0.$$

Definition 3.5. A non-zero vector field X is called a torse-forming vector field on a Riemannian manifold (M, g) [20] if

$$\nabla_U X = fU + \omega(U)X, \quad (3.10)$$

for every vector field U , where ∇ is the Levi-Civita connection of g , f is a function and ω is a 1-form. The particular cases of a torse-forming vector field are listed below:

- (i) If $\omega(U) = 0$ in (3.10), we obtain torqued vector fields [3].
- (ii) If $f = \omega = 0$, we obtain parallel vector fields.
- (iii) If $\omega = 0$ and $f = 1$, we obtain concurrent vector fields [16].
- (iv) If $\omega = 0$, we obtain concircular vector fields [4].

Assume that $(g, X, \alpha, \beta, \nu, \sigma, \zeta)$ is a generalized η -Ricci soliton on an f -Kenmotsu manifold M such that X is a torse-forming vector field. Then we have

$$\alpha\tilde{S}(U, V) + \frac{\beta}{2}(\tilde{L}_X g)(U, V) + \nu X^b(U)X^b(V) + \sigma\eta(U)\eta(V) + \zeta g(U, V) = 0. \quad (3.11)$$

Since

$$(\tilde{L}_X g)(U, V) = 2fg(U, V) + \omega(U)g(X, V) + \omega(V)g(X, U),$$

we rewrite (3.11) as

$$\alpha\tilde{S}(U, V) + [\beta f + \zeta]g(U, V) + \sigma\eta(U)\eta(V) + \frac{\beta}{2}[\omega(U)g(X, V) + \omega(V)g(X, U)] + \nu g(X, U)g(X, V) = 0.$$

Taking contraction in the above equation we get

$$\alpha\tilde{r} + 3[\beta f + \zeta] + \sigma + \beta\omega(X) + \nu|X|^2 = 0.$$

Using (2.12) we can express the final theorem of the paper.

Theorem 3.6. *Let $(M, g, \varphi, \xi, \eta)$ be an f -Kenmotsu manifold admitting the quarter symmetric metric connection defined by (2.7). If M is a generalized η -Ricci soliton with the septet $(g, X, \alpha, \beta, \nu, \sigma, \zeta)$ such that X is a torse-forming vector field, then*

$$\zeta = -\frac{1}{3}[\alpha r + \sigma + \beta\omega(X) + \nu|X|^2] - \beta f.$$

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